

# Global Optimization over Compact Domains

Seminaire Pascaline, LIP, Lyon

Georgy Scholten

MPI-CBG Dresden

Joint work with Mohab Safey El Din and Emmanuel Trélat  
Ongoing work with Alexander Demin

Partially supported by Grant FA8665-20-1-7029 of the EOARD-AFOSR

October 24, 2025



# The Global Optimization Problem

# The Global Optimization Problem

## Problem Statement:

- ▶ Let  $f : \mathcal{C} \rightarrow \mathbb{R}$  be a continuous function on a compact domain  $\mathcal{C} = [-1, 1]^n$

# The Global Optimization Problem

## Problem Statement:

- ▶ Let  $f : \mathcal{C} \rightarrow \mathbb{R}$  be a continuous function on a compact domain  $\mathcal{C} = [-1, 1]^n$
- ▶ **Goal:** Find all local minimizers of  $f$  on  $\mathcal{C}$

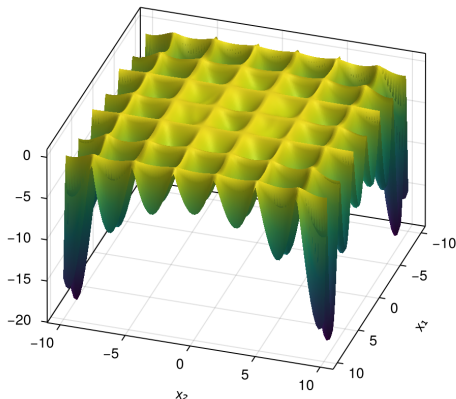
Find all  $x^\star \in \mathcal{C}$  s.t.  $f(x^\star) \leq f(x)$  for all  $x$  near  $x^\star$

# Motivational Example: The Hölder Table Function

$$f(x, y) = -|(\sin(x) \cos(y) \exp(1 - \sqrt{x^2 + y^2}/\pi))|$$

# Motivational Example: The Hölder Table Function

$$f(x, y) = -|(\sin(x) \cos(y) \exp(1 - \sqrt{x^2 + y^2}/\pi))|$$

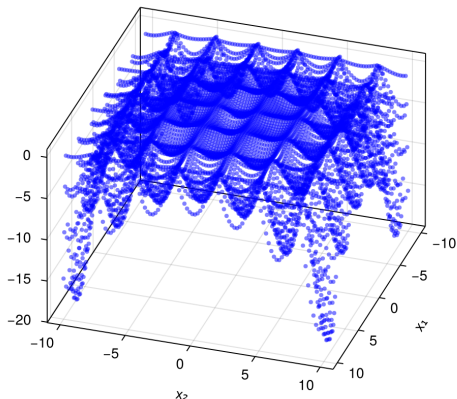


# Motivational Example: The Hölder Table Function

$$f(x, y) = -|(\sin(x) \cos(y) \exp(1 - \sqrt{x^2 + y^2}/\pi))|$$

# Motivational Example: The Hölder Table Function

$$f(x, y) = -|(\sin(x) \cos(y) \exp(1 - \sqrt{x^2 + y^2}/\pi))|$$





# Critical Points Capture of The Hölder Table Function

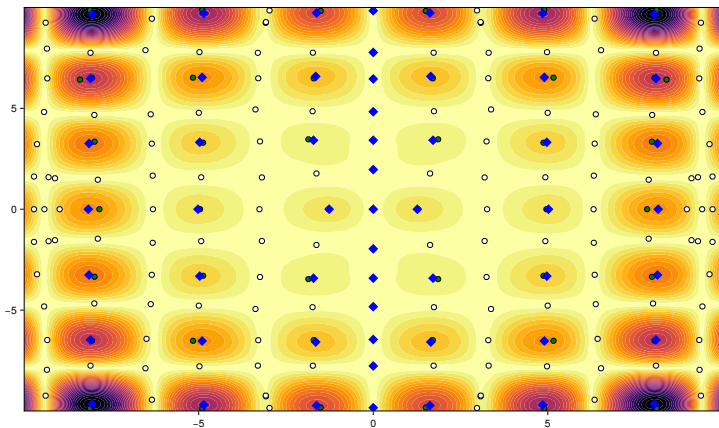


Figure: Level sets and critical points of  $w_{18,s}$

# The Global Optimization Problem (Practical Setting)

# The Global Optimization Problem (Practical Setting)

## Updated Problem Statement:

- ▶ Let  $f : \mathcal{C} \rightarrow \mathbb{R}$  be a continuous function on a compact domain  $\mathcal{C} = [-1, 1]^n$

# The Global Optimization Problem (Practical Setting)

## Updated Problem Statement:

- ▶ Let  $f : \mathcal{C} \rightarrow \mathbb{R}$  be a continuous function on a compact domain  $\mathcal{C} = [-1, 1]^n$
- ▶ **Constraint:** The function  $f$  is only accessible through an *evaluation program*

# The Global Optimization Problem (Practical Setting)

## Updated Problem Statement:

- ▶ Let  $f : \mathcal{C} \rightarrow \mathbb{R}$  be a continuous function on a compact domain  $\mathcal{C} = [-1, 1]^n$
- ▶ **Constraint:** The function  $f$  is only accessible through an *evaluation program*
  - ▶ We can evaluate  $f(x)$  at any point  $x \in \mathcal{C}$

# The Global Optimization Problem (Practical Setting)

## Updated Problem Statement:

- ▶ Let  $f : \mathcal{C} \rightarrow \mathbb{R}$  be a continuous function on a compact domain  $\mathcal{C} = [-1, 1]^n$
- ▶ **Constraint:** The function  $f$  is only accessible through an *evaluation program*
  - ▶ We can evaluate  $f(x)$  at any point  $x \in \mathcal{C}$
  - ▶ No analytical formula is available

# The Global Optimization Problem (Practical Setting)

## Updated Problem Statement:

- ▶ Let  $f : \mathcal{C} \rightarrow \mathbb{R}$  be a continuous function on a compact domain  $\mathcal{C} = [-1, 1]^n$
- ▶ **Constraint:** The function  $f$  is only accessible through an *evaluation program*
  - ▶ We can evaluate  $f(x)$  at any point  $x \in \mathcal{C}$
  - ▶ No analytical formula is available
  - ▶ No derivatives can be computed directly

# The Global Optimization Problem (Practical Setting)

## Updated Problem Statement:

- ▶ Let  $f : \mathcal{C} \rightarrow \mathbb{R}$  be a continuous function on a compact domain  $\mathcal{C} = [-1, 1]^n$
- ▶ **Constraint:** The function  $f$  is only accessible through an *evaluation program*
  - ▶ We can evaluate  $f(x)$  at any point  $x \in \mathcal{C}$
  - ▶ No analytical formula is available
  - ▶ No derivatives can be computed directly
- ▶ **Goal:** Find all local minimizers of  $f$  on  $\mathcal{C}$  ✗



# The Global Optimization Problem (Practical Setting)

## Updated Problem Statement:

- ▶ Let  $f : \mathcal{C} \rightarrow \mathbb{R}$  be a continuous function on a compact domain  $\mathcal{C} = [-1, 1]^n$
- ▶ **Constraint:** The function  $f$  is only accessible through an *evaluation program*
  - ▶ We can evaluate  $f(x)$  at any point  $x \in \mathcal{C}$
  - ▶ No analytical formula is available
  - ▶ No derivatives can be computed directly
- ▶ **Goal:** Find all local minimizers of  $f$  on  $\mathcal{C}$  ✗

# The Global Optimization Problem (Practical Setting)

## Updated Problem Statement:

- ▶ Let  $f : \mathcal{C} \rightarrow \mathbb{R}$  be a continuous function on a compact domain  $\mathcal{C} = [-1, 1]^n$
- ▶ **Constraint:** The function  $f$  is only accessible through an *evaluation program*
  - ▶ We can evaluate  $f(x)$  at any point  $x \in \mathcal{C}$
  - ▶ No analytical formula is available
  - ▶ No derivatives can be computed directly
- ▶ **Goal:** Find all local minimizers of  $f$  on  $\mathcal{C}$  ✗

## We need more assumptions on $f$ :

- ▶ Let  $\text{spec}(f)$  denote eigenvalues of the Hessian of  $f$  at all local minimizers in interior of  $\mathcal{C}$

# The Global Optimization Problem (Practical Setting)

## Updated Problem Statement:

- ▶ Let  $f : \mathcal{C} \rightarrow \mathbb{R}$  be a continuous function on a compact domain  $\mathcal{C} = [-1, 1]^n$
- ▶ **Constraint:** The function  $f$  is only accessible through an *evaluation program*
  - ▶ We can evaluate  $f(x)$  at any point  $x \in \mathcal{C}$
  - ▶ No analytical formula is available
  - ▶ No derivatives can be computed directly
- ▶ **Goal:** Find all local minimizers of  $f$  on  $\mathcal{C}$  ✗

## We need more assumptions on $f$ :

- ▶ Let  $\text{spec}(f)$  denote eigenvalues of the Hessian of  $f$  at all local minimizers in interior of  $\mathcal{C}$
- ▶ For  $\lambda > 0, \rho > 0$  define

$$\mathcal{C}_\lambda^{m,\rho}(\mathcal{C}) = \{f \in \mathcal{M}^m(\mathcal{C}) \mid \min \text{spec}(f) \geq \lambda, \max_{x \in \mathcal{C}} \|d^j f(x)\| \leq \rho, j \leq m\}$$

where  $\mathcal{M}^m(\mathcal{C}) = m$ -times diff. Morse functions on  $\mathcal{C}$

# Overall Methodology: Three-Step Process

# Overall Methodology: Three-Step Process

To compute all local minimizers of  $f$  on  $\mathcal{C}$ , we employ a three-step approach:

# Overall Methodology: Three-Step Process

To compute all local minimizers of  $f$  on  $\mathcal{C}$ , we employ a three-step approach:

1. **Polynomial Approximation Step**

# Overall Methodology: Three-Step Process

To compute all local minimizers of  $f$  on  $\mathcal{C}$ , we employ a three-step approach:

## 1. Polynomial Approximation Step

- ▶ generate a tensorized grid of evaluation points from Chebyshev measure

# Overall Methodology: Three-Step Process

To compute all local minimizers of  $f$  on  $\mathcal{C}$ , we employ a three-step approach:

## 1. Polynomial Approximation Step

- ▶ generate a tensorized grid of evaluation points from Chebyshev measure
- ▶ Create polynomial approximant  $w_{d,s}$  using discrete least-squares



# Overall Methodology: Three-Step Process

To compute all local minimizers of  $f$  on  $\mathcal{C}$ , we employ a three-step approach:

## 1. Polynomial Approximation Step

- ▶ generate a tensorized grid of evaluation points from Chebyshev measure
- ▶ Create polynomial approximant  $w_{d,s}$  using discrete least-squares
- ✓ Good numerical stability over rectangular domains

# Overall Methodology: Three-Step Process

To compute all local minimizers of  $f$  on  $\mathcal{C}$ , we employ a three-step approach:

## 1. Polynomial Approximation Step

- ▶ generate a tensorized grid of evaluation points from Chebyshev measure
- ▶ Create polynomial approximant  $w_{d,s}$  using discrete least-squares
- ✓ Good numerical stability over rectangular domains
- ✓ Control quality via regularity assumptions

# Overall Methodology: Three-Step Process

To compute all local minimizers of  $f$  on  $\mathcal{C}$ , we employ a three-step approach:

## 1. Polynomial Approximation Step

- ▶ generate a tensorized grid of evaluation points from Chebyshev measure
- ▶ Create polynomial approximant  $w_{d,s}$  using discrete least-squares
- ✓ Good numerical stability over rectangular domains
- ✓ Control quality via regularity assumptions

## 2. Algebraic Step

# Overall Methodology: Three-Step Process

To compute all local minimizers of  $f$  on  $\mathcal{C}$ , we employ a three-step approach:

## 1. Polynomial Approximation Step

- ▶ generate a tensorized grid of evaluation points from Chebyshev measure
- ▶ Create polynomial approximant  $w_{d,s}$  using discrete least-squares
- ✓ Good numerical stability over rectangular domains
- ✓ Control quality via regularity assumptions

## 2. Algebraic Step

- ▶ Compute  $\text{crit}(w)$  using algebraic methods

# Overall Methodology: Three-Step Process

To compute all local minimizers of  $f$  on  $\mathcal{C}$ , we employ a three-step approach:

## 1. Polynomial Approximation Step

- ▶ generate a tensorized grid of evaluation points from Chebyshev measure
- ▶ Create polynomial approximant  $w_{d,s}$  using discrete least-squares
- ✓ Good numerical stability over rectangular domains
- ✓ Control quality via regularity assumptions

## 2. Algebraic Step

- ▶ Compute  $\text{crit}(w)$  using algebraic methods
- ▶ Ensure all critical points are captured

# Overall Methodology: Three-Step Process

To compute all local minimizers of  $f$  on  $\mathcal{C}$ , we employ a three-step approach:

## 1. Polynomial Approximation Step

- ▶ generate a tensorized grid of evaluation points from Chebyshev measure
- ▶ Create polynomial approximant  $w_{d,s}$  using discrete least-squares
- ✓ Good numerical stability over rectangular domains
- ✓ Control quality via regularity assumptions

## 2. Algebraic Step

- ▶ Compute  $\text{crit}(w)$  using algebraic methods
- ▶ Ensure all critical points are captured

## 3. Local Optimization

# Overall Methodology: Three-Step Process

To compute all local minimizers of  $f$  on  $\mathcal{C}$ , we employ a three-step approach:

## 1. Polynomial Approximation Step

- ▶ generate a tensorized grid of evaluation points from Chebyshev measure
- ▶ Create polynomial approximant  $w_{d,s}$  using discrete least-squares
- ✓ Good numerical stability over rectangular domains
- ✓ Control quality via regularity assumptions

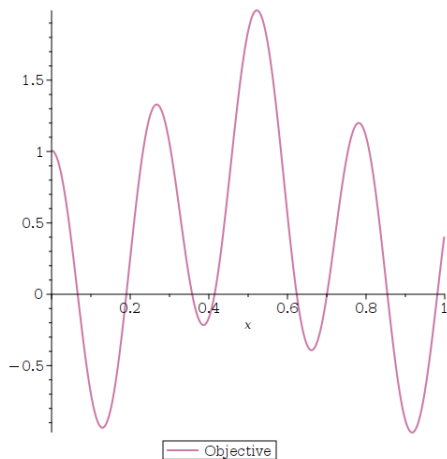
## 2. Algebraic Step

- ▶ Compute  $\text{crit}(w)$  using algebraic methods
- ▶ Ensure all critical points are captured

## 3. Local Optimization

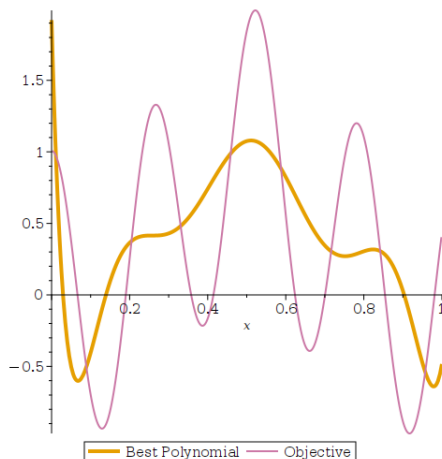
- ▶ Initiate local optimization methods at the computed points

# $L^\infty$ vs $L^2$ Polynomial Approximant



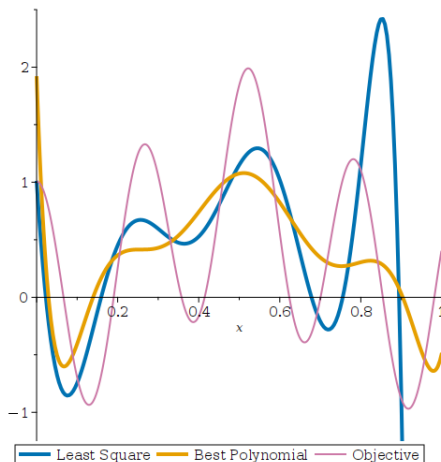


# $L^\infty$ vs $L^2$ Polynomial Approximant



$$\|f\|_{\mathcal{L}^\infty} = \max_{x \in \mathbb{C}} |f(x)|. \quad (1)$$

# $L^\infty$ vs $L^2$ Polynomial Approximant



$$\|f\|_{\mathcal{L}^2} = \left( \int_{\mathcal{C}} f(x)^2 d\mu \right)^{\frac{1}{2}}. \quad (2)$$

# Chebyshev Polynomials

---

<sup>1</sup>Keaton J. Burns et al. “Dedalus: A flexible framework for numerical simulations with spectral methods”. *Phys. Rev. Res.* 2 (2 Apr. 2020), p. 023068. DOI: 10.1103/PhysRevResearch.2.023068. URL: <https://link.aps.org/doi/10.1103/PhysRevResearch.2.023068>.

# Chebyshev Polynomials

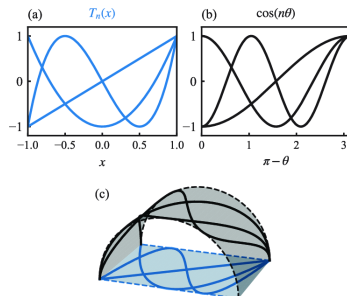


Figure: Dedalus<sup>1</sup>

<sup>1</sup>Keaton J. Burns et al. "Dedalus: A flexible framework for numerical simulations with spectral methods". *Phys. Rev. Res.* 2 (2 Apr. 2020), p. 023068. DOI: [10.1103/PhysRevResearch.2.023068](https://doi.org/10.1103/PhysRevResearch.2.023068). URL: <https://link.aps.org/doi/10.1103/PhysRevResearch.2.023068>.

# Chebyshev Polynomials

# Chebyshev Polynomials

- Orthogonality:

$$\int_{\mathcal{C}} T_m(x) T_n(x) d\mu = \gamma_n \delta_{mn}$$

where  $\gamma_n > 0$

---

<sup>a</sup>Zaïneb Bel-Afia, Chiara Meroni, and Simon Telen. *Chebyshev Varieties*. 2024. arXiv: 2401.12140 [math.AG]. URL: <https://arxiv.org/abs/2401.12140>.

# Chebyshev Polynomials

- Orthogonality:

$$\int_{\mathcal{C}} T_m(x) T_n(x) d\mu = \gamma_n \delta_{mn}$$

where  $\gamma_n > 0$

- Well-suited for solving Least Squares

---

<sup>a</sup>Zaïneb Bel-Afia, Chiara Meroni, and Simon Telen. *Chebyshev Varieties*. 2024. arXiv: 2401.12140 [math.AG]. URL: <https://arxiv.org/abs/2401.12140>.

# Chebyshev Polynomials

- Orthogonality:

$$\int_{\mathcal{C}} T_m(x) T_n(x) d\mu = \gamma_n \delta_{mn}$$

where  $\gamma_n > 0$

- Well-suited for solving Least Squares
- Chebyshev Varieties<sup>a</sup>:

$$x_1^{v_1} \dots x_n^{v_n} \rightarrow T_{v_1}(x_1) \dots T_{v_n}(x_n)$$

---

<sup>a</sup>Zaïneb Bel-Afia, Chiara Meroni, and Simon Telen. *Chebyshev Varieties*. 2024. arXiv: 2401.12140 [math.AG]. URL: <https://arxiv.org/abs/2401.12140>.



# Chebyshev Polynomials

- Orthogonality:

$$\int_{\mathcal{C}} T_m(x) T_n(x) d\mu = \gamma_n \delta_{mn}$$

where  $\gamma_n > 0$

- Well-suited for solving Least Squares
- Chebyshev Varieties<sup>a</sup>:

$$x_1^{v_1} \dots x_n^{v_n} \rightarrow T_{v_1}(x_1) \dots T_{v_n}(x_n)$$

---

<sup>a</sup>Zaïneb Bel-Afia, Chiara Meroni, and Simon Telen. *Chebyshev Varieties*. 2024. arXiv: 2401.12140 [math.AG]. URL: <https://arxiv.org/abs/2401.12140>.

# Chebyshev Polynomials

- Orthogonality:

$$\int_{\mathcal{C}} T_m(x) T_n(x) d\mu = \gamma_n \delta_{mn}$$

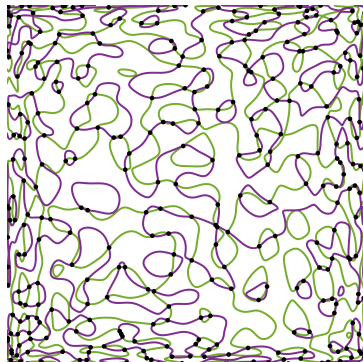
where  $\gamma_n > 0$

- Well-suited for solving Least Squares
- Chebyshev Varieties<sup>a</sup>:

$$x_1^{v_1} \dots x_n^{v_n} \rightarrow T_{v_1}(x_1) \dots T_{v_n}(x_n)$$

---

<sup>a</sup>Zaïneb Bel-Afia, Chiara Meroni, and Simon Telen. *Chebyshev Varieties*. 2024. arXiv: 2401.12140 [math.AG]. URL: <https://arxiv.org/abs/2401.12140>.



# Jackson's Approximation Theorem

# Jackson's Approximation Theorem

## $\rho$ -Regularity

Let  $f \in \mathcal{C}_\lambda^{m,\rho}(\mathbb{C})$ , meaning:

$$\max_{x \in \mathbb{C}} \|d^j f(x)\| \leq \rho \quad \text{for all } j \leq m$$

# Jackson's Approximation Theorem

## $\rho$ -Regularity

Let  $f \in \mathcal{C}_\lambda^{m,\rho}(\mathbb{C})$ , meaning:

$$\max_{x \in \mathbb{C}} \|d^j f(x)\| \leq \rho \quad \text{for all } j \leq m$$

## Jackson's Theorem

There exists a constant  $C_{n,m} > 0$  such that:

$$\min_{p \in \mathcal{P}_{n,d}} \max_{x \in \mathbb{C}} |f(x) - p(x)| \leq C_{n,m} \frac{\rho}{d^{m-1}}$$

# Jackson's Approximation Theorem

## $\rho$ -Regularity

Let  $f \in \mathcal{C}_\lambda^{m,\rho}(\mathbb{C})$ , meaning:

$$\max_{x \in \mathbb{C}} \|d^j f(x)\| \leq \rho \quad \text{for all } j \leq m$$

## Jackson's Theorem

There exists a constant  $C_{n,m} > 0$  such that:

$$\min_{p \in \mathcal{P}_{n,d}} \max_{x \in \mathbb{C}} |f(x) - p(x)| \leq C_{n,m} \frac{\rho}{d^{m-1}}$$

- ▶ Error decreases as  $\mathcal{O}(d^{-(m-1)})$  with polynomial degree  $d$

# Jackson's Approximation Theorem

## $\rho$ -Regularity

Let  $f \in \mathcal{C}_\lambda^{m,\rho}(\mathbb{C})$ , meaning:

$$\max_{x \in \mathbb{C}} \|d^j f(x)\| \leq \rho \quad \text{for all } j \leq m$$

## Jackson's Theorem

There exists a constant  $C_{n,m} > 0$  such that:

$$\min_{p \in \mathcal{P}_{n,d}} \max_{x \in \mathbb{C}} |f(x) - p(x)| \leq C_{n,m} \frac{\rho}{d^{m-1}}$$

- ▶ Error decreases as  $\mathcal{O}(d^{-(m-1)})$  with polynomial degree  $d$
- ▶ Higher smoothness  $m \Rightarrow$  faster convergence rate

# Jackson's Approximation Theorem

## $\rho$ -Regularity

Let  $f \in \mathcal{C}_\lambda^{m,\rho}(\mathbb{C})$ , meaning:

$$\max_{x \in \mathbb{C}} \|d^j f(x)\| \leq \rho \quad \text{for all } j \leq m$$

## Jackson's Theorem

There exists a constant  $C_{n,m} > 0$  such that:

$$\min_{p \in \mathcal{P}_{n,d}} \max_{x \in \mathbb{C}} |f(x) - p(x)| \leq C_{n,m} \frac{\rho}{d^{m-1}}$$

- ▶ Error decreases as  $\mathcal{O}(d^{-(m-1)})$  with polynomial degree  $d$
- ▶ Higher smoothness  $m \Rightarrow$  faster convergence rate
- ▶ Constant  $C_{n,m}$  depends on dimension  $n$  and smoothness  $m$



# Main Theorem [Safey El Din, S., Trélat]

# Main Theorem [Safey El Din, S., Trélat]

Let  $f \in \mathcal{C}_\lambda^{m,\rho}(\mathbb{C})$  with  $m \geq \max(3, \beta n + 1)$ , where  $\beta = \frac{\ln(3)}{2\ln(2)}$ .

Let  $r > 0$  satisfy  $\rho r \leq 3\lambda$ ,  $\alpha \in (0, 1)$  and  $C_{n,m}$  the Jackson constant.

# Main Theorem [Safey El Din, S., Trélat]

Let  $f \in \mathcal{C}_\lambda^{m,\rho}(\mathbb{C})$  with  $m \geq \max(3, \beta n + 1)$ , where  $\beta = \frac{\ln(3)}{2\ln(2)}$ .

Let  $r > 0$  satisfy  $\rho r \leq 3\lambda$ ,  $\alpha \in (0, 1)$  and  $C_{n,m}$  the Jackson constant.

Given any  $\delta \in (0, 1)$ , set

$$A_1 = 16 \left( \frac{1}{\pi^n} + \frac{2}{1-\delta} \right) \frac{C_{n,m}^2 \rho^2}{(\pi e)^n} \quad \text{and} \quad A_2 = \frac{16(1+\delta)}{(\pi e)^n (1-\delta)^2} \left( 8\delta^2(1-\delta)^4 + 4 \right).$$

# Main Theorem [Safey El Din, S., Trélat]

Let  $f \in \mathcal{C}_\lambda^{m,\rho}(\mathbb{C})$  with  $m \geq \max(3, \beta n + 1)$ , where  $\beta = \frac{\ln(3)}{2\ln(2)}$ .

Let  $r > 0$  satisfy  $\rho r \leq 3\lambda$ ,  $\alpha \in (0, 1)$  and  $C_{n,m}$  the Jackson constant.

Given any  $\delta \in (0, 1)$ , set

$$A_1 = 16 \left( \frac{1}{\pi^n} + \frac{2}{1-\delta} \right) \frac{C_{n,m}^2 \rho^2}{(\pi e)^n} \quad \text{and} \quad A_2 = \frac{16(1+\delta)}{(\pi e)^n (1-\delta)^2} \left( 8\delta^2(1-\delta)^4 + 4 \right).$$

If  $d \in \mathbb{N}$  satisfies the **degree condition**:

$$\left( \frac{A_1}{d^{2m-2}} + A_2 \varepsilon^2 \right) d^{2\beta n} \leq \lambda^2 r^4,$$

# Main Theorem [Safey El Din, S., Trélat]

Let  $f \in \mathcal{C}_\lambda^{m,\rho}(\mathbb{C})$  with  $m \geq \max(3, \beta n + 1)$ , where  $\beta = \frac{\ln(3)}{2\ln(2)}$ .

Let  $r > 0$  satisfy  $\rho r \leq 3\lambda$ ,  $\alpha \in (0, 1)$  and  $C_{n,m}$  the Jackson constant.

Given any  $\delta \in (0, 1)$ , set

$$A_1 = 16 \left( \frac{1}{\pi^n} + \frac{2}{1-\delta} \right) \frac{C_{n,m}^2 \rho^2}{(\pi e)^n} \quad \text{and} \quad A_2 = \frac{16(1+\delta)}{(\pi e)^n (1-\delta)^2} \left( 8\delta^2 (1-\delta)^4 + 4 \right).$$

If  $d \in \mathbb{N}$  satisfies the **degree condition**:

$$\left( \frac{A_1}{d^{2m-2}} + A_2 \varepsilon^2 \right) d^{2\beta n} \leq \lambda^2 r^4,$$

then with a large enough sample set  $\mathcal{S}$  chosen from the Chebyshev measure:

the DLSP approximant  $w_{d,\mathcal{S}}$  **captures all local minimizers**  
at precision  $r$  with probability  $\geq 1 - \alpha$

# Main Theorem [Safey El Din, S., Trélat]

Let  $f \in \mathcal{C}_\lambda^{m,\rho}(\mathbb{C})$  with  $m \geq \max(3, \beta n + 1)$ , where  $\beta = \frac{\ln(3)}{2\ln(2)}$ .

Let  $r > 0$  satisfy  $\rho r \leq 3\lambda$ ,  $\alpha \in (0, 1)$  and  $C_{n,m}$  the Jackson constant.

Given any  $\delta \in (0, 1)$ , set

$$A_1 = 16 \left( \frac{1}{\pi^n} + \frac{2}{1-\delta} \right) \frac{C_{n,m}^2 \rho^2}{(\pi e)^n} \quad \text{and} \quad A_2 = \frac{16(1+\delta)}{(\pi e)^n (1-\delta)^2} \left( 8\delta^2 (1-\delta)^4 + 4 \right).$$

If  $d \in \mathbb{N}$  satisfies the **degree condition**:

$$\left( \frac{A_1}{d^{2m-2}} + A_2 \varepsilon^2 \right) d^{2\beta n} \leq \lambda^2 r^4,$$

then with a large enough sample set  $\mathcal{S}$  chosen from the Chebyshev measure:

the DLSP approximant  $w_{d,\mathcal{S}}$  **captures all local minimizers**  
at precision  $r$  with probability  $\geq 1 - \alpha$

**Constants dependency:**

- ▶  $A_1$ : dimension  $n$ , smoothness  $m$ , regularity  $\rho$ , parameter  $\delta$
- ▶  $A_2$ : dimension  $n$ , parameter  $\delta$

# Probabilistic Least Squares Polynomials

# Probabilistic Least Squares Polynomials

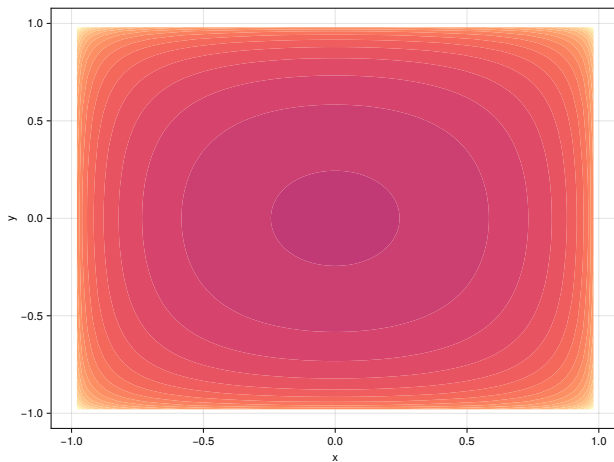


Figure: probability density of  $\mu$ .



# Probabilistic Least Squares Polynomials

# Probabilistic Least Squares Polynomials

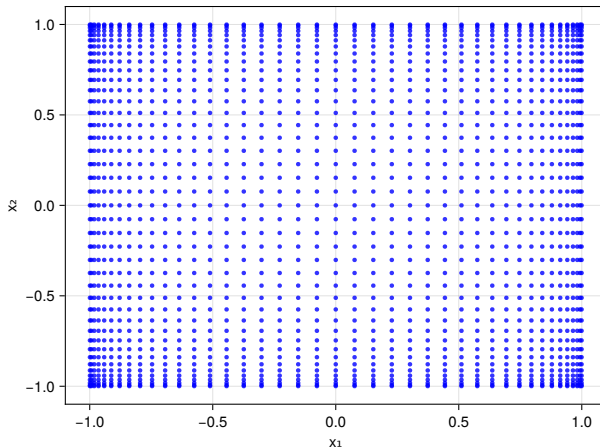


Figure: Discretization of  $\mu$ .

# Probabilistic Least Squares Polynomials

# Probabilistic Least Squares Polynomials

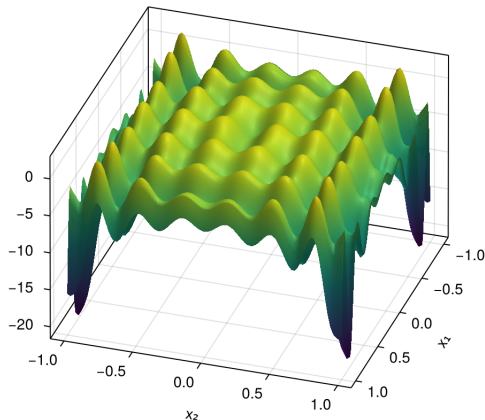


Figure:  $w_{18}$

# Probabilistic Least Squares Polynomials

# Probabilistic Least Squares Polynomials

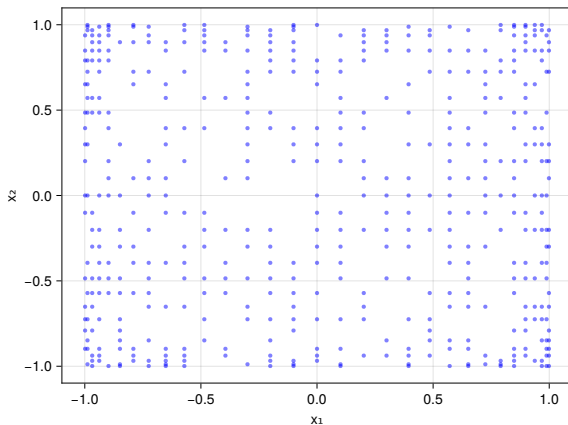


Figure: reduced sample set  $\mathcal{S}$ .

# Probabilistic Least Squares Polynomials

# Probabilistic Least Squares Polynomials

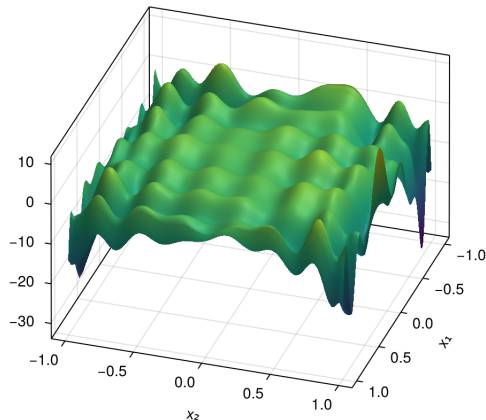


Figure:  $w_{18,S}$ .



# Probabilistic Bounds

---

<sup>2</sup>Giovanni Migliorati, Fabio Nobile, and Raúl Tempone. “Convergence estimates in probability and in expectation for discrete least-squares with noisy evaluations at random points”. *Journal of Multivariate Analysis* 142 (2015), pp. 167–182. ISSN: 0047-259X. DOI: <https://doi.org/10.1016/j.jmva.2015.08.009>. URL: <https://www.sciencedirect.com/science/article/pii/S0047259X15001931>.

# Probabilistic Bounds

**Theorem:**<sup>2</sup> if the number of samples  $k$  satisfies

$$\frac{\binom{n+d}{n}^{\frac{\ln(3)}{2\ln(2)}}}{\delta + (1-\delta)\ln(1-\delta)} \leq \frac{k}{\ln(k) + \ln(6\alpha^{-1})}, \quad (3)$$

then with probability at least  $1 - \alpha$ , we have

$$\|w_{d,S} - f\|_{\mathcal{L}^2}^2 \leq \left(1 + \frac{C(\delta)}{\alpha \ln(6k\alpha^{-1})}\right) e_d(f)^2, \quad (4)$$

where

$$C(\delta) = \frac{4(\delta + (1-\delta)\ln(1-\delta))}{(1-\delta)^2}, \quad (5)$$

---

<sup>2</sup>Giovanni Migliorati, Fabio Nobile, and Raúl Tempone. “Convergence estimates in probability and in expectation for discrete least-squares with noisy evaluations at random points”. *Journal of Multivariate Analysis* 142 (2015), pp. 167–182. ISSN: 0047-259X. DOI: <https://doi.org/10.1016/j.jmva.2015.08.009>. URL: <https://www.sciencedirect.com/science/article/pii/S0047259X15001931>.

# Practical Considerations

- ▶ Converting to standard monomial basis
- ▶ Computing partial derivatives
- ▶ Computing critical points:
  1. `Msolve`

# Practical Considerations

- ▶ Converting to standard monomial basis
- ▶ Computing partial derivatives
- ▶ Computing critical points:
  1. `Msolve`
  2. `HomotopyContinuation.jl`

# Practical Considerations

- ▶ Converting to standard monomial basis
- ▶ Computing partial derivatives
- ▶ Computing critical points:
  1. Msolve
  2. HomotopyContinuation.jl
  3. Bertini Real

# Practical Considerations

- ▶ Converting to standard monomial basis
- ▶ Computing partial derivatives
- ▶ Computing critical points:
  1. Msolve
  2. HomotopyContinuation.jl
  3. Bertini Real
  4. HypersurfaceRegions.jl (?)

# Convergence in $L^2$

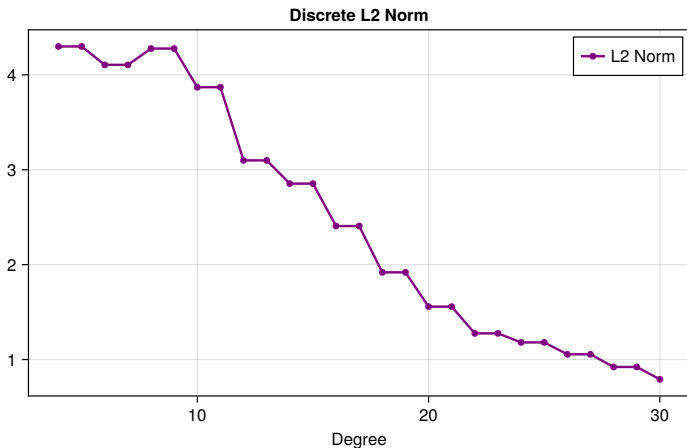


Figure: Error in  $\mathcal{L}^2$ -norm of the approximant

# Convergence of Local Minimizers

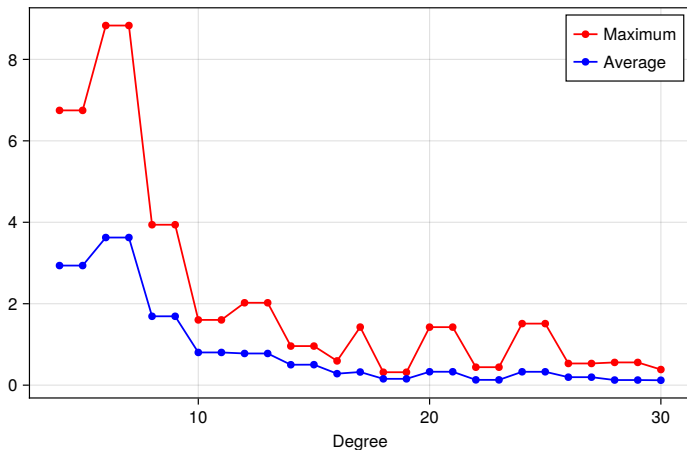


Figure: Distance from local minimizers to nearest critical point.



# Tolerance to Noise

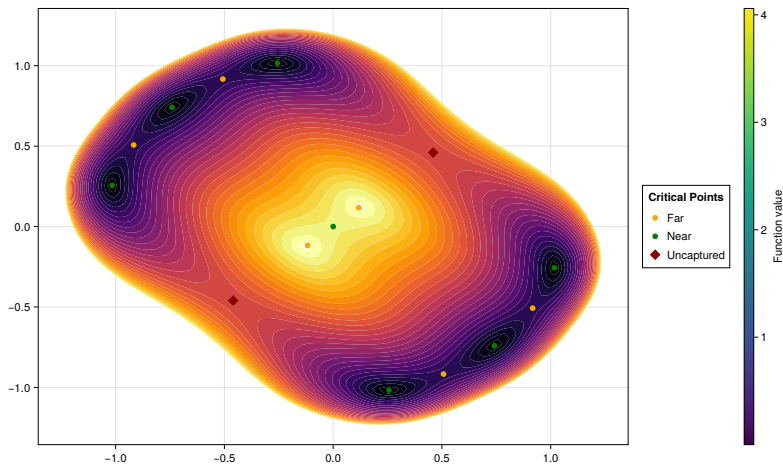


Figure: Deuffhard function

# Tolerance to Noise

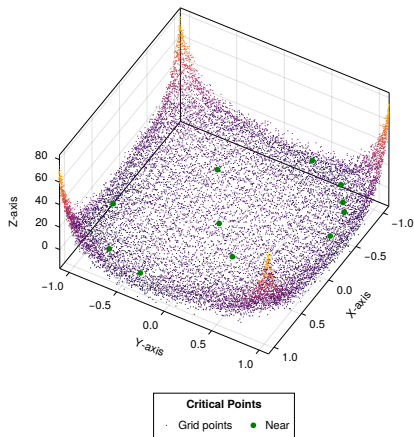


Figure: Noisy Deuffhard function

# Tolerance to Noise

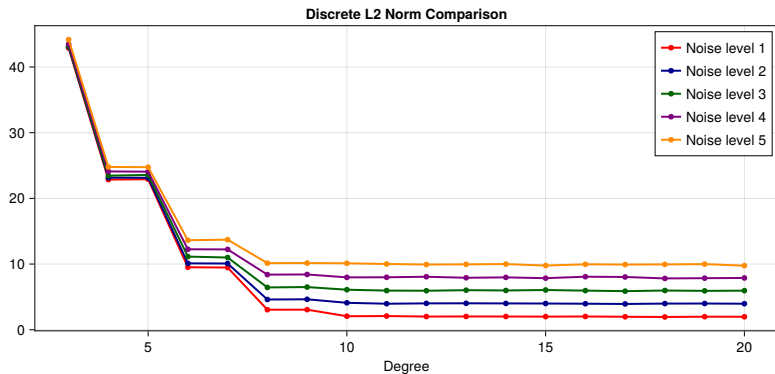


Figure: Noisy Deuffhard L2-norm approximation

# Tolerance to Noise

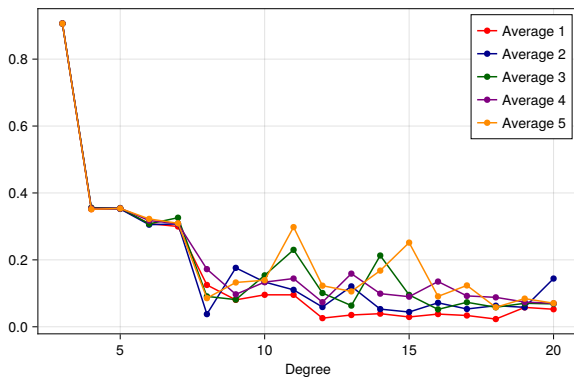


Figure: Noisy Deuffhard convergence of critical points

# 3D Function Example

$$f(x, y, z) = e^{\sin(50x_1)} + \sin(60e^{x_2}) \sin(60x_3) + \sin(70 \sin(x_1)) \cos(10x_3) \\ + \sin(\sin(80x_2)) - \sin(10(x_1 + x_3)) + \frac{x_1^2 + x_2^2 + x_3^2}{4} \quad (6)$$

# ODE System: Parameter Estimation Problem

# ODE System: Parameter Estimation Problem

Consider a system of ODEs in the state-space form:

$$\Sigma := \begin{cases} \mathbf{x}'(t) = \mathbf{f}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{y}(t) = \mathbf{g}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{x}(0) = \mathbf{x}_0, \end{cases}$$

# ODE System: Parameter Estimation Problem

Consider a system of ODEs in the state-space form:

$$\Sigma := \begin{cases} \mathbf{x}'(t) = \mathbf{f}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{y}(t) = \mathbf{g}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{x}(0) = \mathbf{x}_0, \end{cases}$$

where:

- ▶  $\mathbf{x}(t)$ : state variables



# ODE System: Parameter Estimation Problem

Consider a system of ODEs in the state-space form:

$$\Sigma := \begin{cases} \mathbf{x}'(t) = \mathbf{f}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{y}(t) = \mathbf{g}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{x}(0) = \mathbf{x}_0, \end{cases}$$

where:

- ▶  $\mathbf{x}(t)$ : state variables
- ▶  $\mathbf{y}(t)$ : output variables (observables)

# ODE System: Parameter Estimation Problem

Consider a system of ODEs in the state-space form:

$$\Sigma := \begin{cases} \mathbf{x}'(t) = \mathbf{f}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{y}(t) = \mathbf{g}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{x}(0) = \mathbf{x}_0, \end{cases}$$

where:

- ▶  $\mathbf{x}(t)$ : state variables
- ▶  $\mathbf{y}(t)$ : output variables (observables)
- ▶  $\boldsymbol{\mu}$ : scalar parameters (to be estimated)

# ODE System: Parameter Estimation Problem

Consider a system of ODEs in the state-space form:

$$\Sigma := \begin{cases} \mathbf{x}'(t) = \mathbf{f}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{y}(t) = \mathbf{g}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{x}(0) = \mathbf{x}_0, \end{cases}$$

where:

- ▶  $\mathbf{x}(t)$ : state variables
- ▶  $\mathbf{y}(t)$ : output variables (observables)
- ▶  $\boldsymbol{\mu}$ : scalar parameters (to be estimated)
- ▶  $\mathbf{u}(t)$ : input variables (control)

# ODE System: Parameter Estimation Problem

Consider a system of ODEs in the state-space form:

$$\Sigma := \begin{cases} \mathbf{x}'(t) = \mathbf{f}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{y}(t) = \mathbf{g}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{x}(0) = \mathbf{x}_0, \end{cases}$$

where:

- ▶  $\mathbf{x}(t)$ : state variables
- ▶  $\mathbf{y}(t)$ : output variables (observables)
- ▶  $\boldsymbol{\mu}$ : scalar parameters (to be estimated)
- ▶  $\mathbf{u}(t)$ : input variables (control)
- ▶  $\mathbf{f}$  and  $\mathbf{g}$ : rational functions in  $\mathbf{x}(t), \boldsymbol{\mu}, \mathbf{u}(t)$

# ODE System: Parameter Estimation Problem

Consider a system of ODEs in the state-space form:

$$\Sigma := \begin{cases} \mathbf{x}'(t) = \mathbf{f}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{y}(t) = \mathbf{g}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{x}(0) = \mathbf{x}_0, \end{cases}$$

where:

- ▶  $\mathbf{x}(t)$ : state variables
- ▶  $\mathbf{y}(t)$ : output variables (observables)
- ▶  $\boldsymbol{\mu}$ : scalar parameters (to be estimated)
- ▶  $\mathbf{u}(t)$ : input variables (control)
- ▶  $\mathbf{f}$  and  $\mathbf{g}$ : rational functions in  $\mathbf{x}(t), \boldsymbol{\mu}, \mathbf{u}(t)$

# ODE System: Parameter Estimation Problem

Consider a system of ODEs in the state-space form:

$$\Sigma := \begin{cases} \mathbf{x}'(t) = \mathbf{f}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{y}(t) = \mathbf{g}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\mu}), \\ \mathbf{x}(0) = \mathbf{x}_0, \end{cases}$$

where:

- ▶  $\mathbf{x}(t)$ : state variables
- ▶  $\mathbf{y}(t)$ : output variables (observables)
- ▶  $\boldsymbol{\mu}$ : scalar parameters (to be estimated)
- ▶  $\mathbf{u}(t)$ : input variables (control)
- ▶  $\mathbf{f}$  and  $\mathbf{g}$ : rational functions in  $\mathbf{x}(t), \boldsymbol{\mu}, \mathbf{u}(t)$

**Given data:**  $D = ((t_1, \mathbf{y}_1), \dots, (t_n, \mathbf{y}_n))$ , where  $\mathbf{y}_i$  is measured at time  $t_i$

# Constructing the Objective Function

# Constructing the Objective Function

Let  $\mu$  be the parameters to be estimated.



# Constructing the Objective Function

Let  $\mu$  be the parameters to be estimated.

Take time points  $\{t_1, t_2, \dots, t_N\}$  and let  $\mu \in \mathbb{R}^n$

$$f(\mu) = \sum_{i=1}^N \left( \mathbf{y}(t_i; \mu) - \mathbf{y}_{\text{target}}(t_i) \right)^2$$

where  $\mathbf{y}(t_i; \mu)$  is the computed response at time  $t_i$  for parameters  $\mu$ , and  $\mathbf{y}_{\text{target}}(t_i)$  is the target response.

# Constructing the Objective Function

Let  $\mu$  be the parameters to be estimated.

Take time points  $\{t_1, t_2, \dots, t_N\}$  and let  $\mu \in \mathbb{R}^n$

$$f(\mu) = \sum_{i=1}^N \left( \mathbf{y}(t_i; \mu) - \mathbf{y}_{\text{target}}(t_i) \right)^2$$

where  $\mathbf{y}(t_i; \mu)$  is the computed response at time  $t_i$  for parameters  $\mu$ , and  $\mathbf{y}_{\text{target}}(t_i)$  is the target response.

Take a sample set  $\mathcal{S} \in \mathbb{R}^n$  and construct

$$w_d := \operatorname{argmin}_{p \in \mathcal{P}_{n,d}} \sum_{s \in \mathcal{S}} (p(s) - f(s))^2$$

# Constructing the Objective Function

Let  $\mu$  be the parameters to be estimated.

Take time points  $\{t_1, t_2, \dots, t_N\}$  and let  $\mu \in \mathbb{R}^n$

$$f(\mu) = \sum_{i=1}^N \left( \mathbf{y}(t_i; \mu) - \mathbf{y}_{\text{target}}(t_i) \right)^2$$

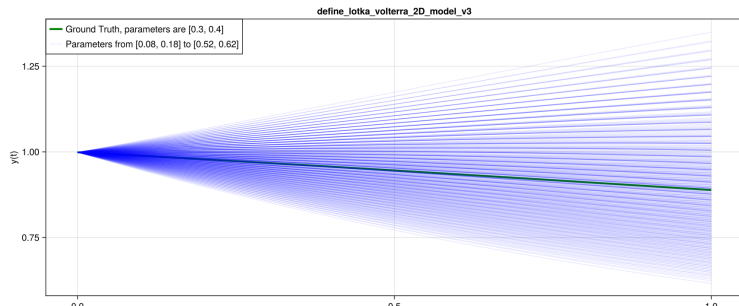
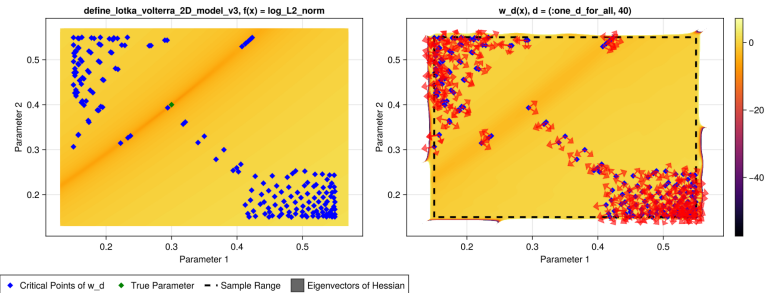
where  $\mathbf{y}(t_i; \mu)$  is the computed response at time  $t_i$  for parameters  $\mu$ , and  $\mathbf{y}_{\text{target}}(t_i)$  is the target response.

Take a sample set  $\mathcal{S} \in \mathbb{R}^n$  and construct

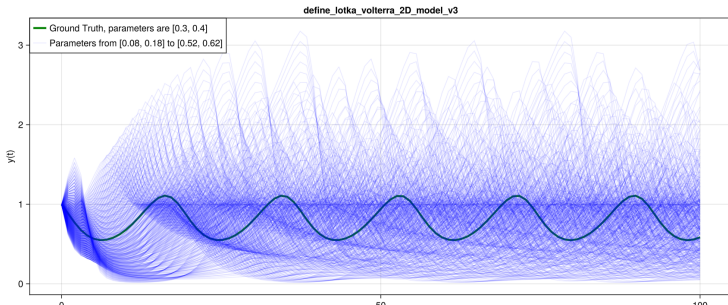
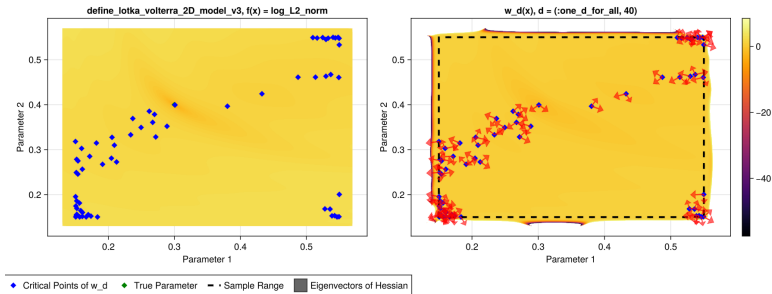
$$w_d := \operatorname{argmin}_{p \in \mathcal{P}_{n,d}} \sum_{s \in \mathcal{S}} (p(s) - f(s))^2$$

The recovered critical points serve as initial guesses for local optimization methods.

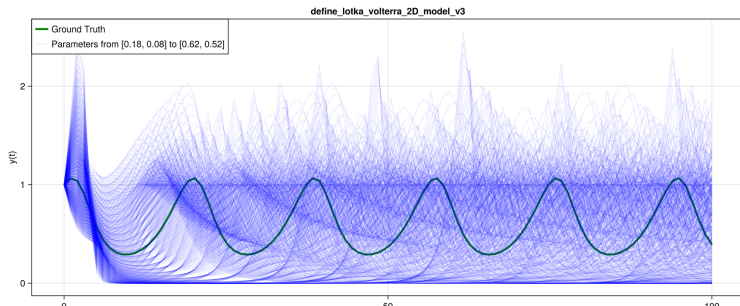
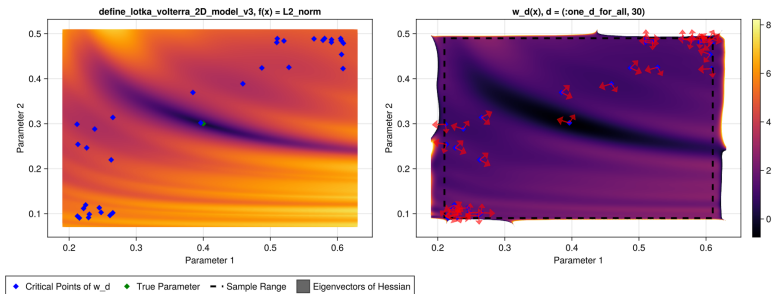
# Parameter Estimation Lotka-Volterra: (t=1)



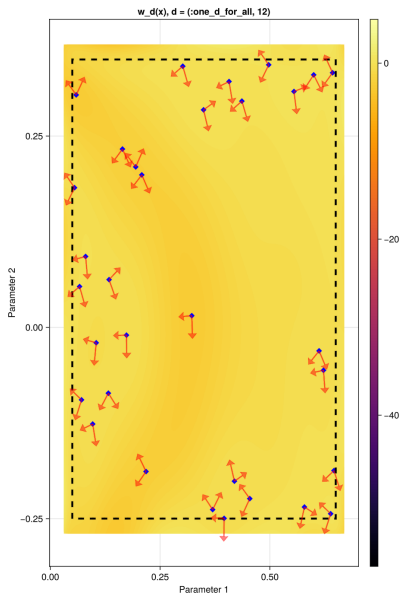
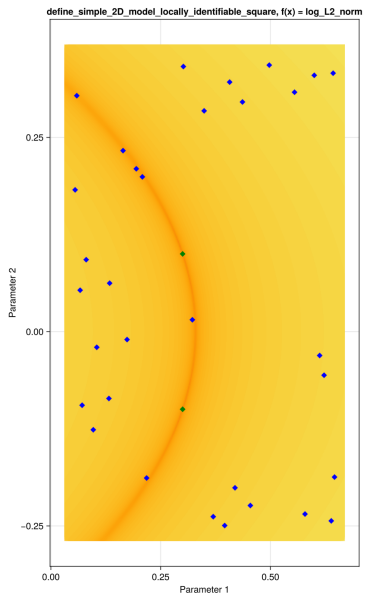
# Parameter Estimation Lotka-Volterra (t=100)



# Parameter Estimation Lotka-Volterra (t=100)



# Locally Identifiable Model



# Thank You! I

- ▶ Matthieu Dolbeault, David Krieg, and Mario Ullrich. “A sharp upper bound for sampling numbers in  $\mathcal{L}^2$ ”. *Applied and Computational Harmonic Analysis* 63 (2023), pp. 113–134. ISSN: 1063-5203. DOI: <https://doi.org/10.1016/j.acha.2022.12.001>. URL: <https://www.sciencedirect.com/science/article/pii/S1063520322000999>
- ▶ Albert Cohen and Giovanni Migliorati. “Optimal weighted least-squares methods”. en. *The SMAI Journal of computational mathematics* 3 (2017), pp. 181–203. DOI: 10.5802/smai-jcm.24. URL: <https://smai-jcm.centre-mersenne.org/articles/10.5802/smai-jcm.24/>
- ▶ Mohab Safey El Din, Georgy Scholten, and Emmanuel Trélat. “Probabilistic algorithm for computing all local minimizers of Morse functions on a compact domain”. working paper or preprint. 2025. URL: <https://hal.sorbonne-universite.fr/hal-05160251>